

PlatonicGAN

Escaping Plato's Cave: 3D Shapes From Adversarial Rendering

Philipp Henzler

Niloy J. Mitra

Tobias Ritschel

University College London

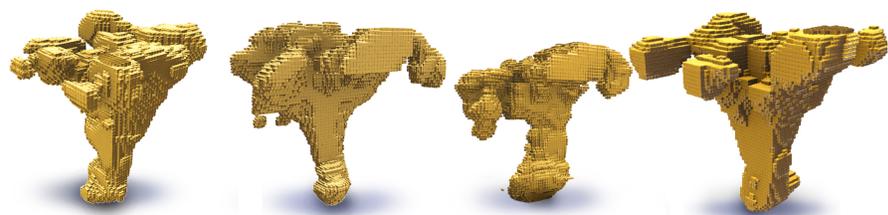


Motivation

Input: 2D image collection (different object, view, light, camera, etc.)



Output: Generative 3D model



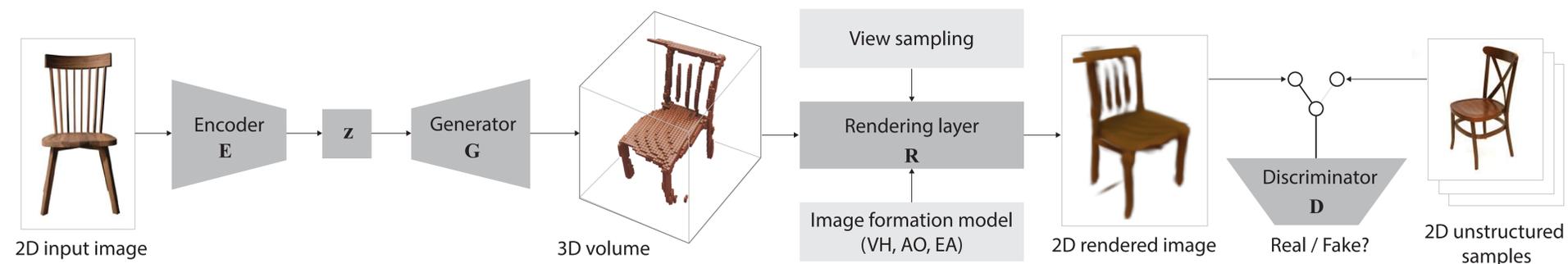
Contribution

1. Adversarial training of 3D generator with 2D discriminator that operates exclusively on widely available unstructured collections of images, i.e. no relation among images is known.
2. Family of differentiable rendering layers.

Degree of supervision

	[1] Kanazawa et al.	[2] Kato et al.	[3] Eslami et al.	[4] Tulsiani et al.	[5] Tulsiani et al.	[6] PrGAN	[Ours]
Supervision at training time	-	+	+	+	+	+	+
Annotation-free	-	+	+	+	+	+	+
3D template-free	-	-	+	+	+	+	+
Unknown camera pose	+	-	-	-	+	+	+
No pre-defined camera poses	+	+	+	+	-	-	+
Only single view required	+	-	-	-	-	+	+
Color	+	+	+	+	-	-	+

Overview



Rendering layers

a) Visual Hull

$$\rho_{VH}(\mathbf{v}) = 1 - \exp\left(\sum_i -v_i\right)$$

a) VH

b) Absorption Only

$$\rho_{AO}(\mathbf{v}) = 1 - \prod_i (1 - v_i)$$

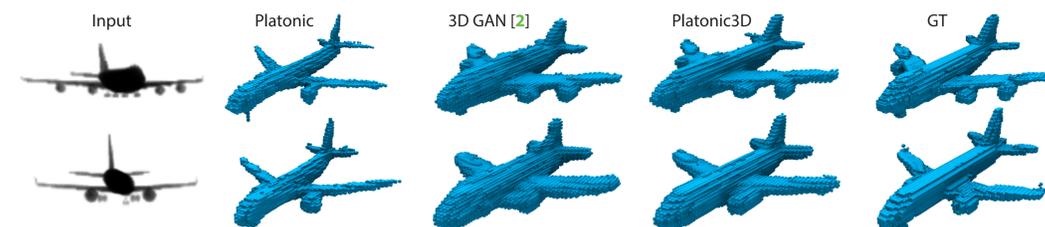
b) AO

c) Emission Absorption

$$\rho_{EA}(\mathbf{v}) = \sum_{i=1}^{n_z} \left(1 - \prod_{j=1}^i (1 - v_{a,j})\right)$$

c) EA

Comparison



Results



References

- [1] Angjoo Kanazawa, Shubham Tulsiani, Alexei A. Efros, and Jitendra Malik. Learning category-specific mesh reconstruction from image collections. In ECCV, 2018.
- [2] Hiroharu Kato, Yoshitaka Ushiku, and Tatsuya Harada. Neural 3D mesh renderer. In CVPR, 2018.
- [3] SM Ali Eslami, Danilo Jimenez Rezende, Frederic Besse, Fabio Viola, Ari S Morcos, Marta Garnelo, Avraham Ruderman, Andrei A Rusu, Ivo Danihelka, Karol Gregor, et al. Neural scene representation and rendering. Science, 2018.
- [4] Shubham Tulsiani, Tinghui Zhou, Alexei A Efros, and Ji-tendra Malik. Multi-view supervision for single-view reconstruction via differentiable ray consistency. In CVPR, 2017.
- [5] Shubham Tulsiani, Alexei A Efros, and Jitendra Malik. Multi-view consistency as supervisory signal for learning shape and pose prediction. In CVPR, 2018.
- [6] Mathus Gadelha, Subhransu Maji, and Rui Wang. 3d shape induction from 2d views of multiple objects. In 3DV, 2016.
- [7] Jiajun Wu, Chengkai Zhang, Tianfan Xue, Bill Freeman, and Josh Tenenbaum. Learning a probabilistic latent space of object shapes via 3D generative-adversarial modeling. In NIPS, 2016.

Algorithm

Algorithm: PLATONICGAN Reconstruction Update Step

- 1: $I_{Dat} \leftarrow \text{SAMPLEIMAGE}(p_{Dat})$
- 2: $\omega \leftarrow \text{SAMPLEVIEW}(p_{View})$
- 3: $z \leftarrow E(I_{Dat})$
- 4: $v \leftarrow G(z)$
- 5: $I_{View} \leftarrow R(\omega, v)$
- 6: $I_{Front} \leftarrow R(\omega_0, v)$
- 7: $c_{Dis} \leftarrow \log D(I_{Dat}) + \log(1 - D(I_{View}))$
- 8: $c_{Gen} \leftarrow \log(1 - D(I_{View}))$
- 9: $c_{Rec} \leftarrow L2(I_{Dat} - I_{Front})$
- 10: $\Psi \leftarrow \text{MAXIMIZE}(c_{Dis})$
- 11: $\Theta, \Phi \leftarrow \text{MINIMIZE}(c_{Gen} + \lambda c_{Rec})$

Acknowledgements

This work was supported by the ERC Starting Grant SmartGeometry, a GPU donation by NVIDIA Corporation and a Google AR/VR Research Award.

Email: p.henzler@cs.ucl.ac.uk
Website: https://henzler.github.io/

