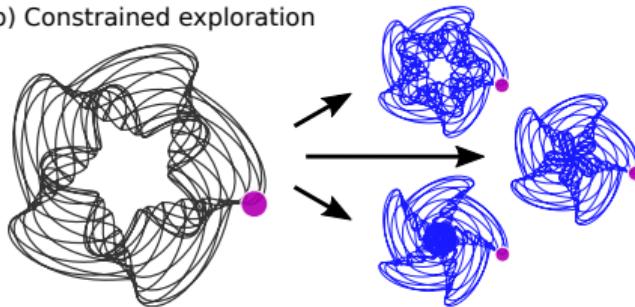


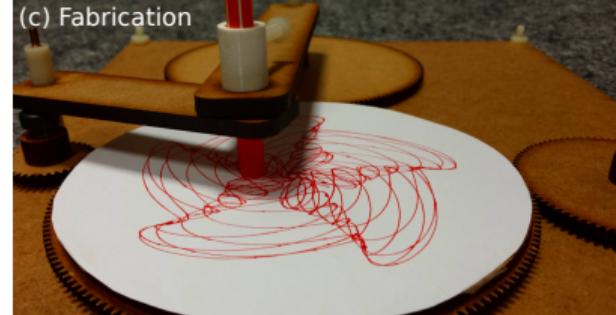
(a) Coarse sketch



(b) Constrained exploration



(c) Fabrication



SPIROU: Constrained Exploration for Mechanical Motion Design

Symposium on Computational Fabrication

Robin Roussel ^{1,2} **Marie-Paule Cani** ² **Jean-Claude Léon** ² **Niloy J. Mitra** ¹

¹University College London ²Grenoble-Alpes University and Inria

June 13, 2017

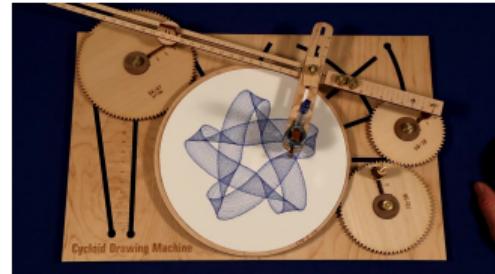
Drawing machines



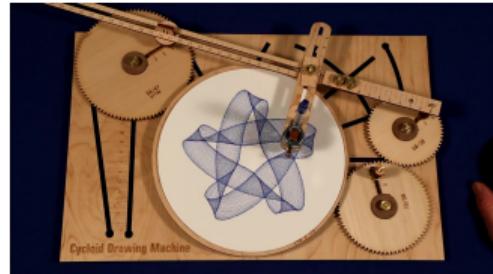
Drawing machines



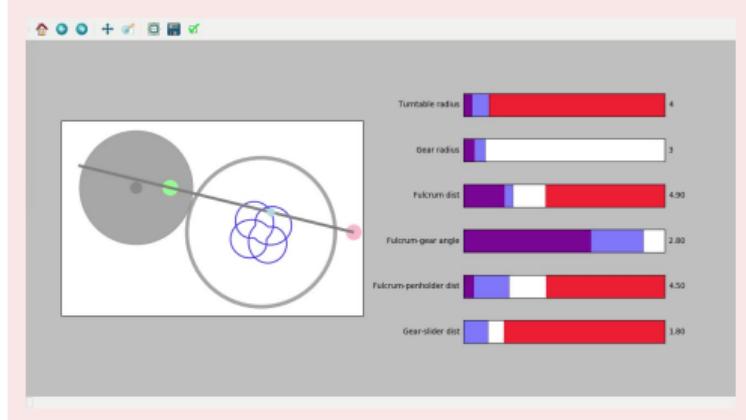
Drawing machines



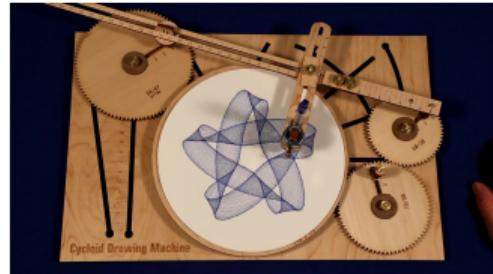
Drawing machines



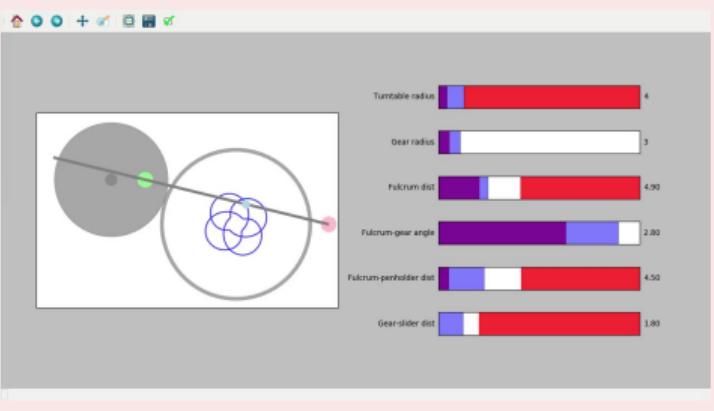
Problem



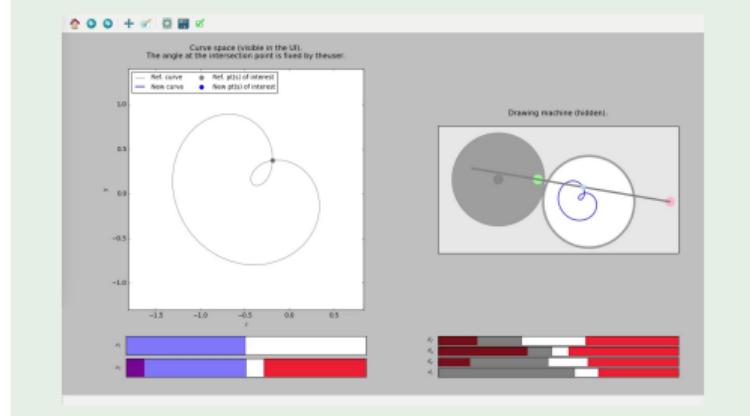
Drawing machines



Problem



Objective



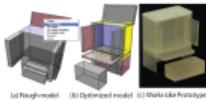
Related work and contributions

		What is designed	
		Shape	Motion
Design process	Query and optimization		
	Constrained exploration		

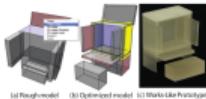
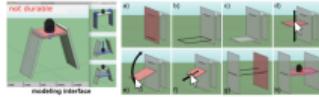
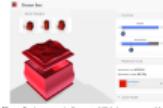
Related work and contributions

		What is designed	
		Shape	Motion
Design process	Query and optimization		[Coros et al. 2013]
	Constrained exploration		[Bächer et al. 2015] 

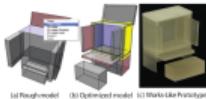
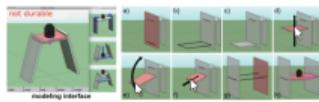
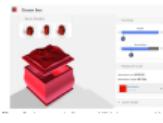
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		Shape	Motion
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	Constrained exploration	 [Umetani et al. 2012]	 [Shugrina et al. 2015]

Related work and contributions

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	Constrained exploration	 [Umetani et al. 2012]	 [Shugrina et al. 2015]
		Our method	

Outline

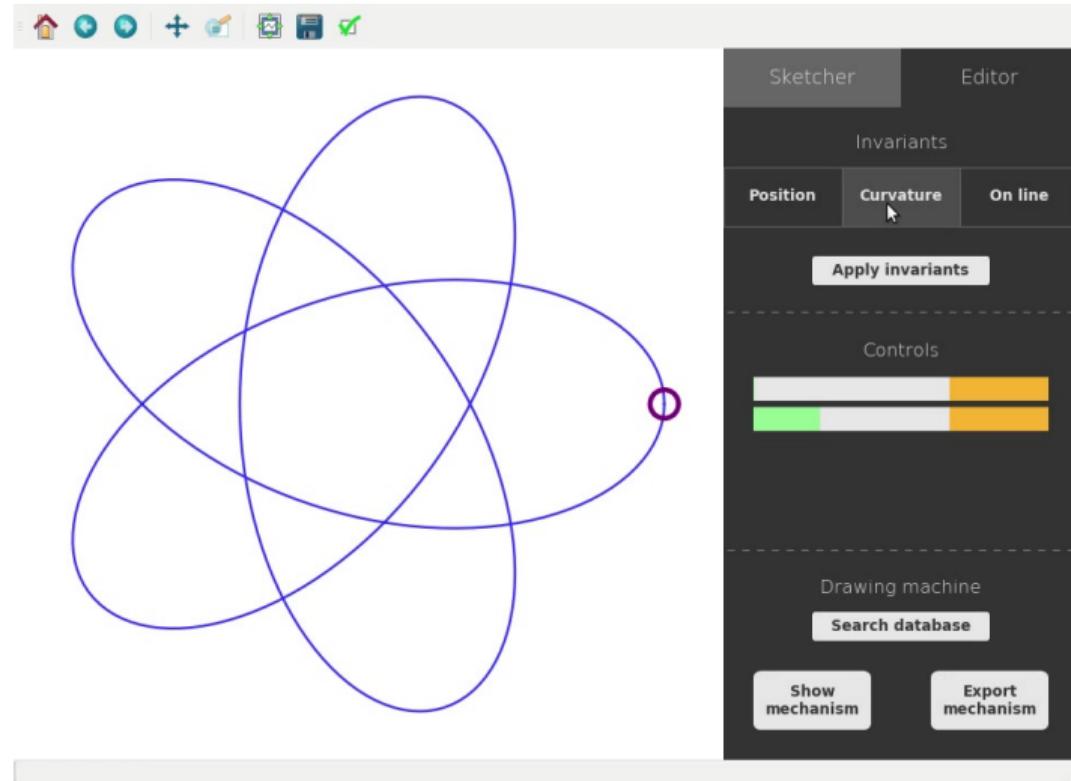
Introduction

Method

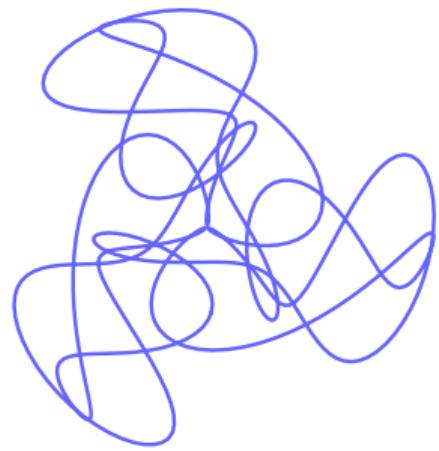
Results

Conclusion

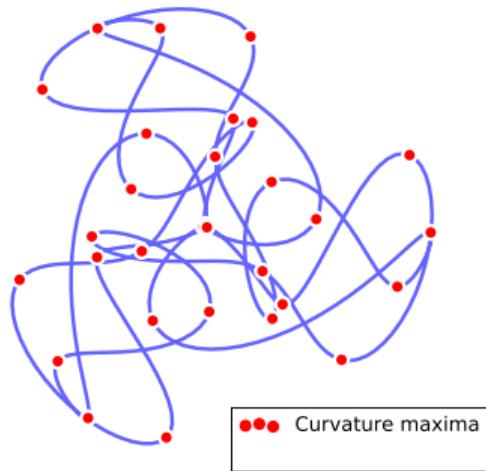
Workflow



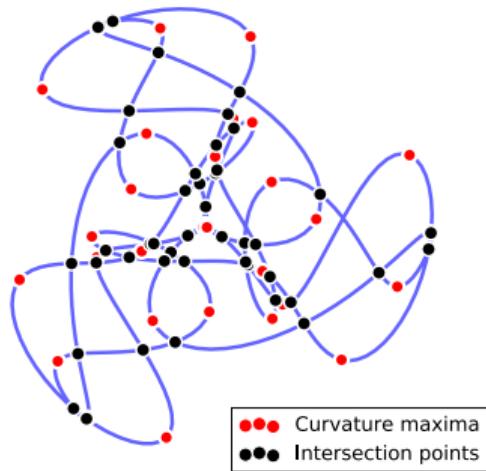
Points of interest and invariants



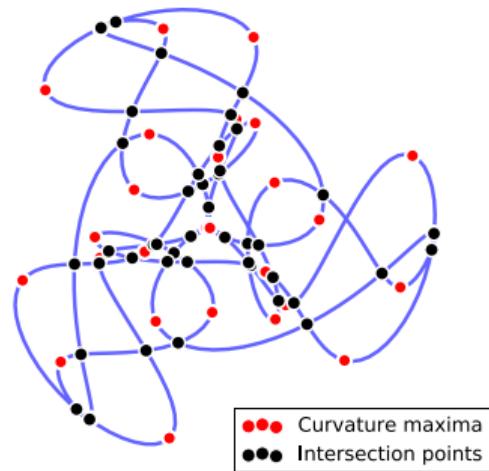
Points of interest and invariants



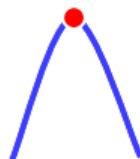
Points of interest and invariants



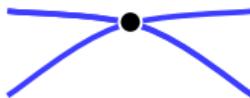
Points of interest and invariants



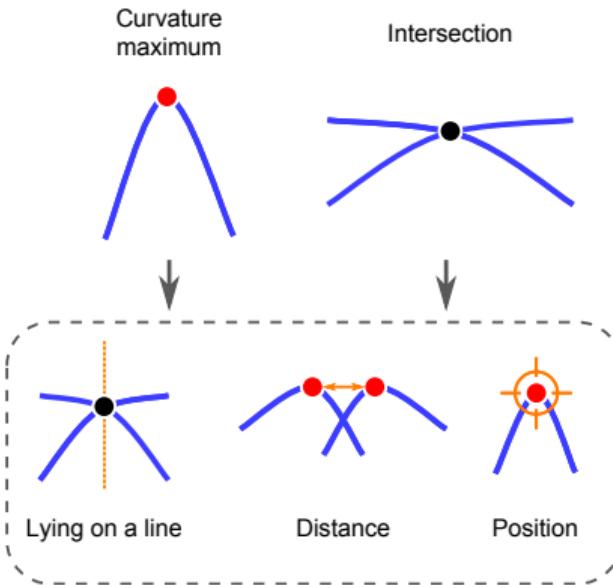
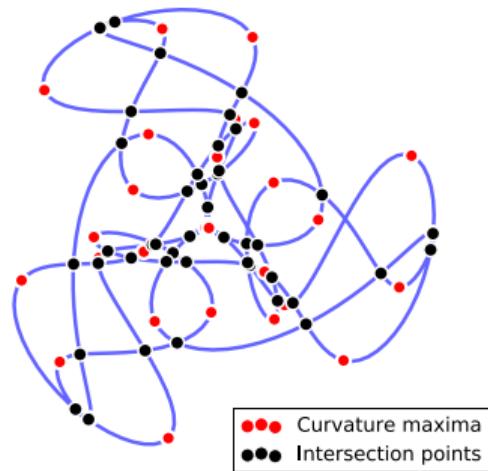
Curvature maximum



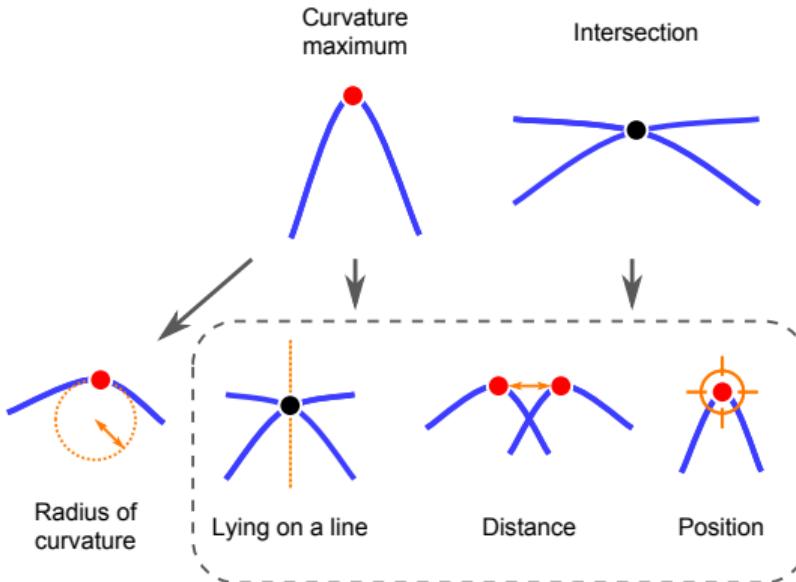
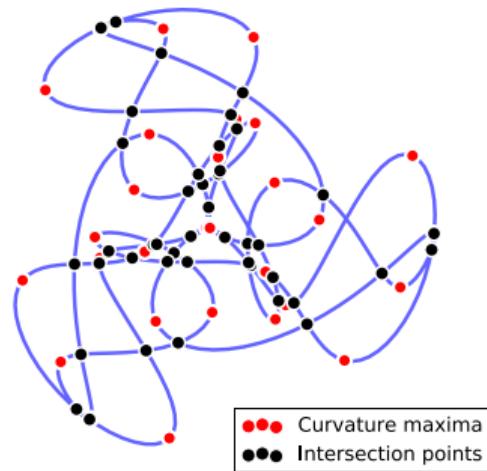
Intersection



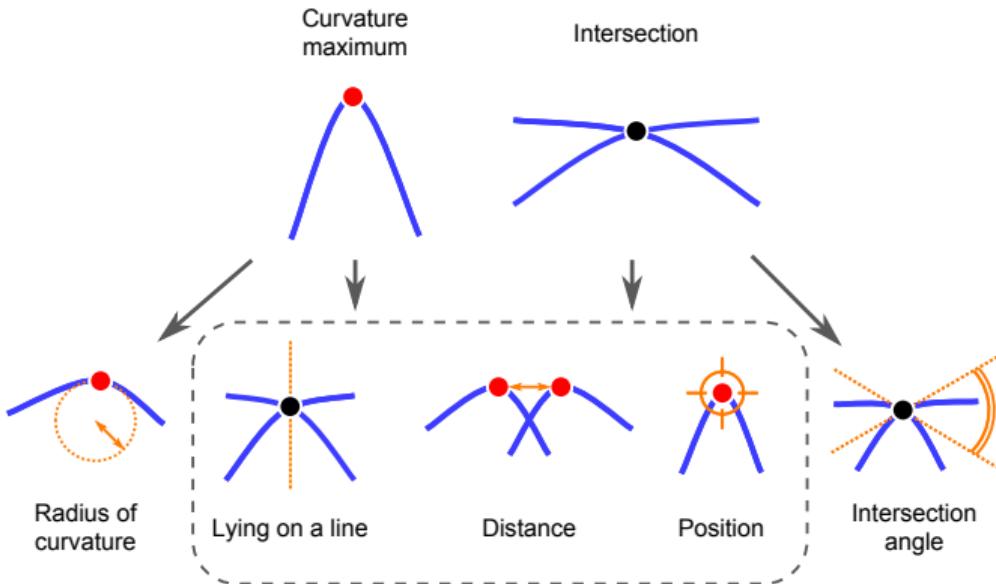
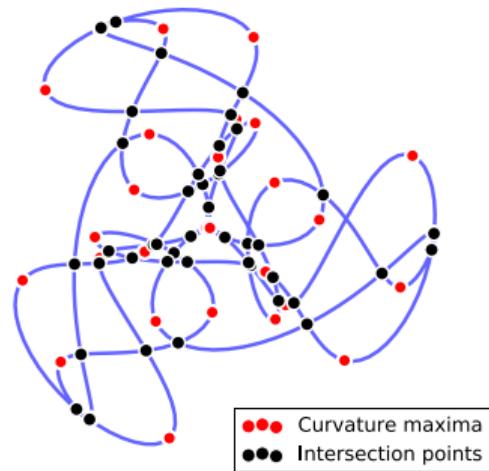
Points of interest and invariants



Points of interest and invariants



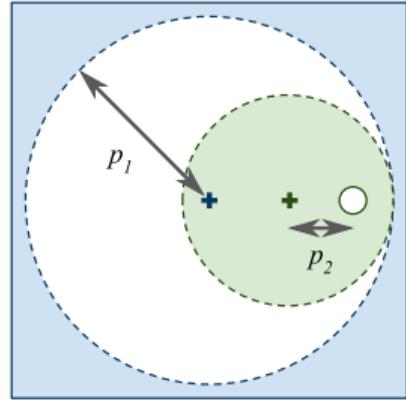
Points of interest and invariants



Implementation

Internal representation

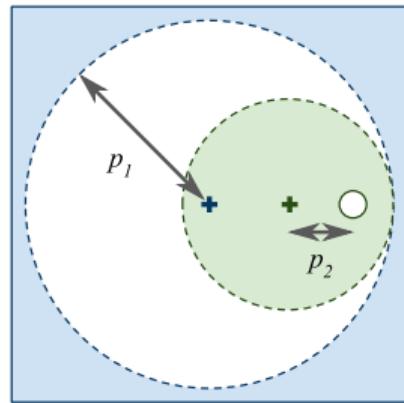
Parametric model



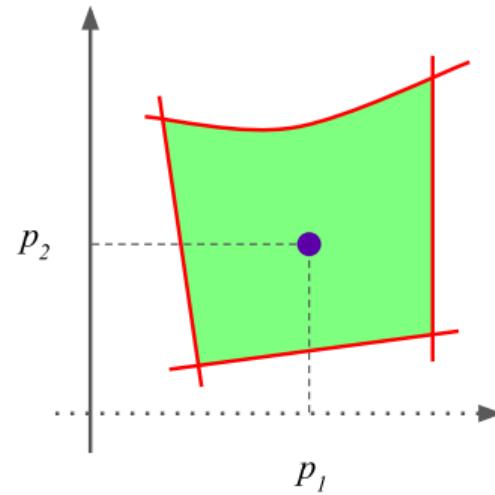
Implementation

Internal representation

Parametric model



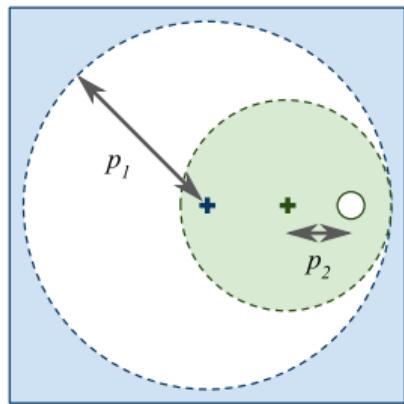
Design space



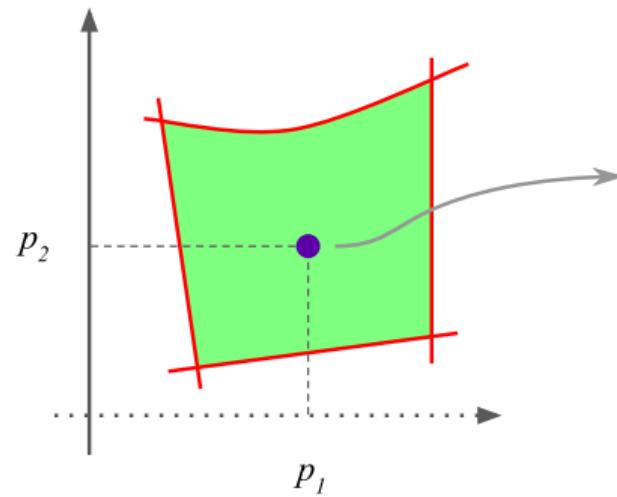
Implementation

Internal representation

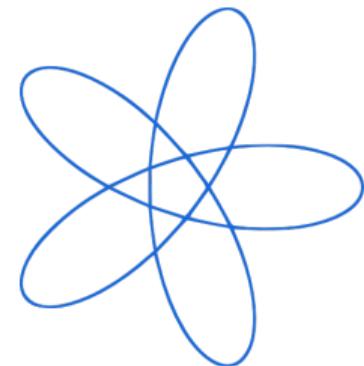
Parametric model



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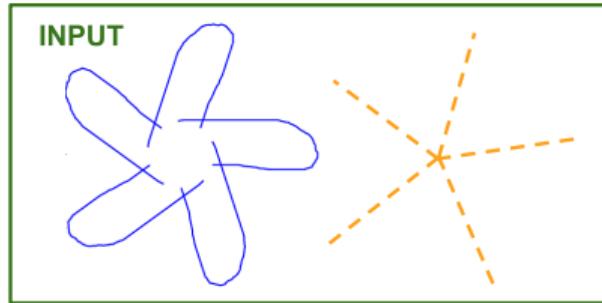


Simulator



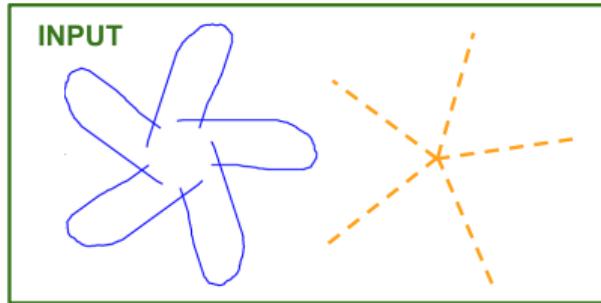
Implementation

Sketch-based retrieval

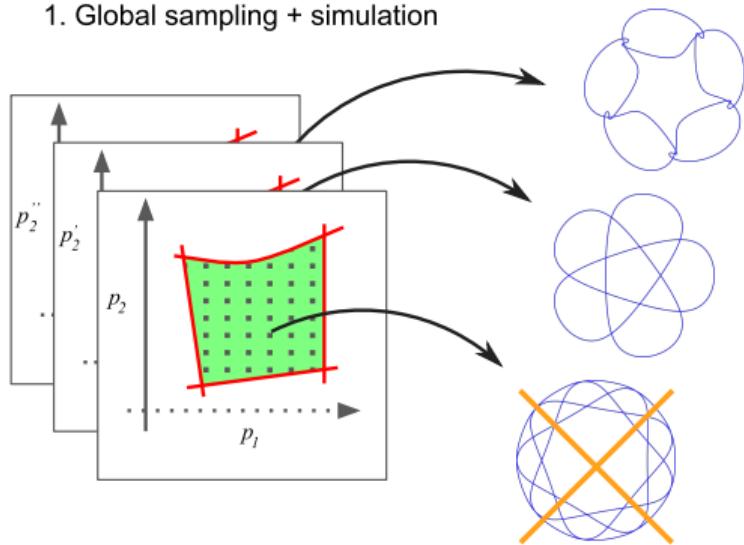


Implementation

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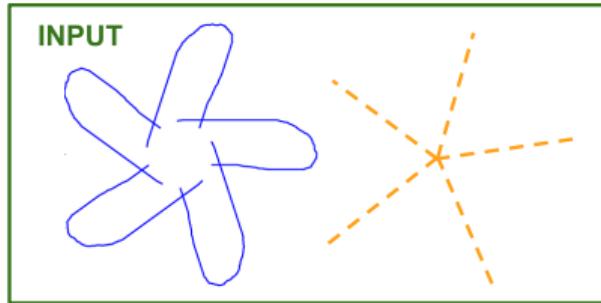


1. Global sampling + simulation

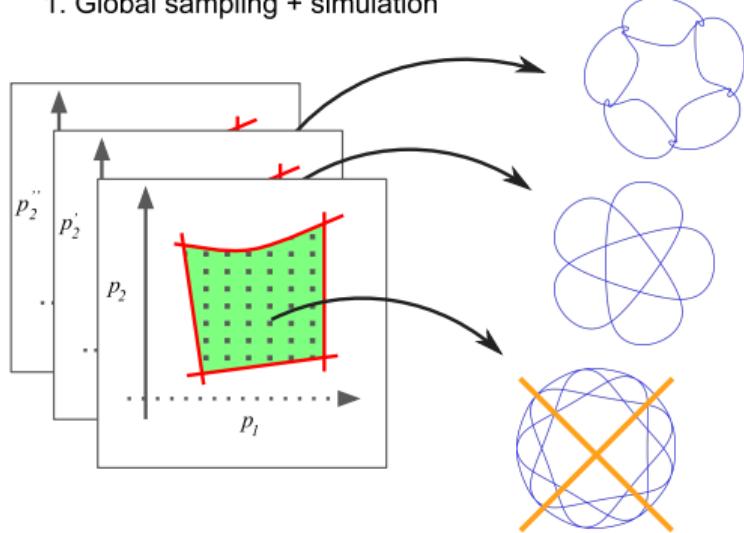


Implementation

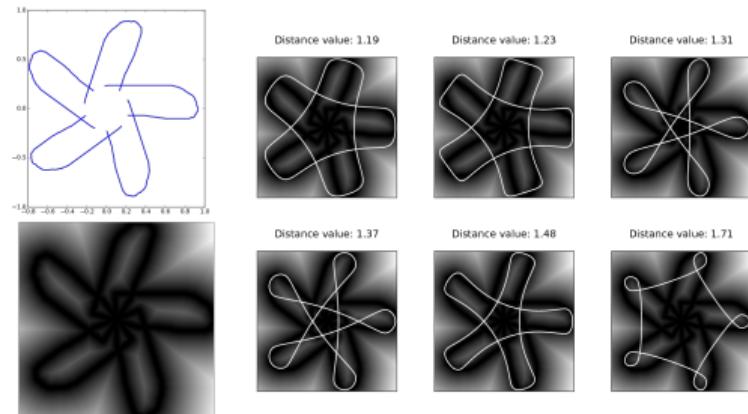
Sketch-based retrieval



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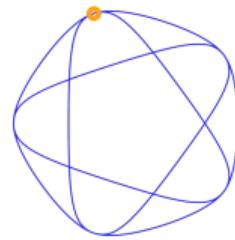


2. Normalization + Dissimilarity evaluation



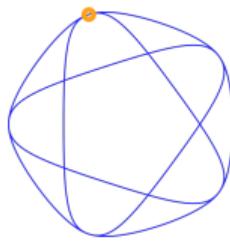
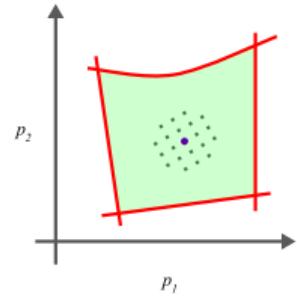
Implementation

Invariance score



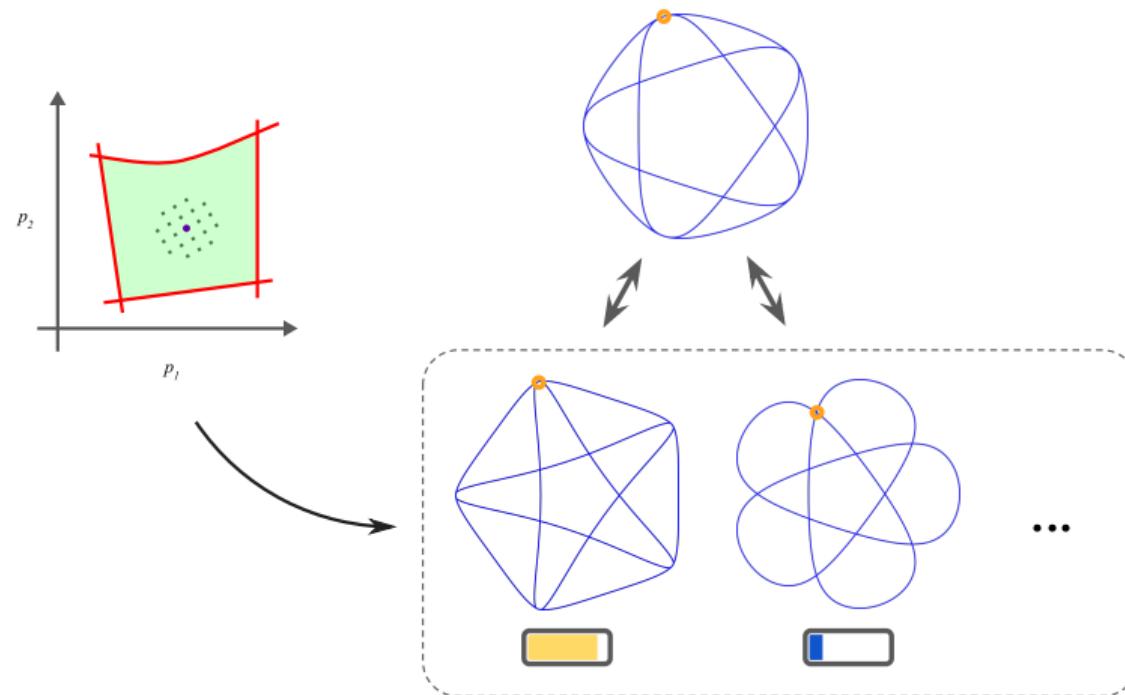
Implementation

Invariance score



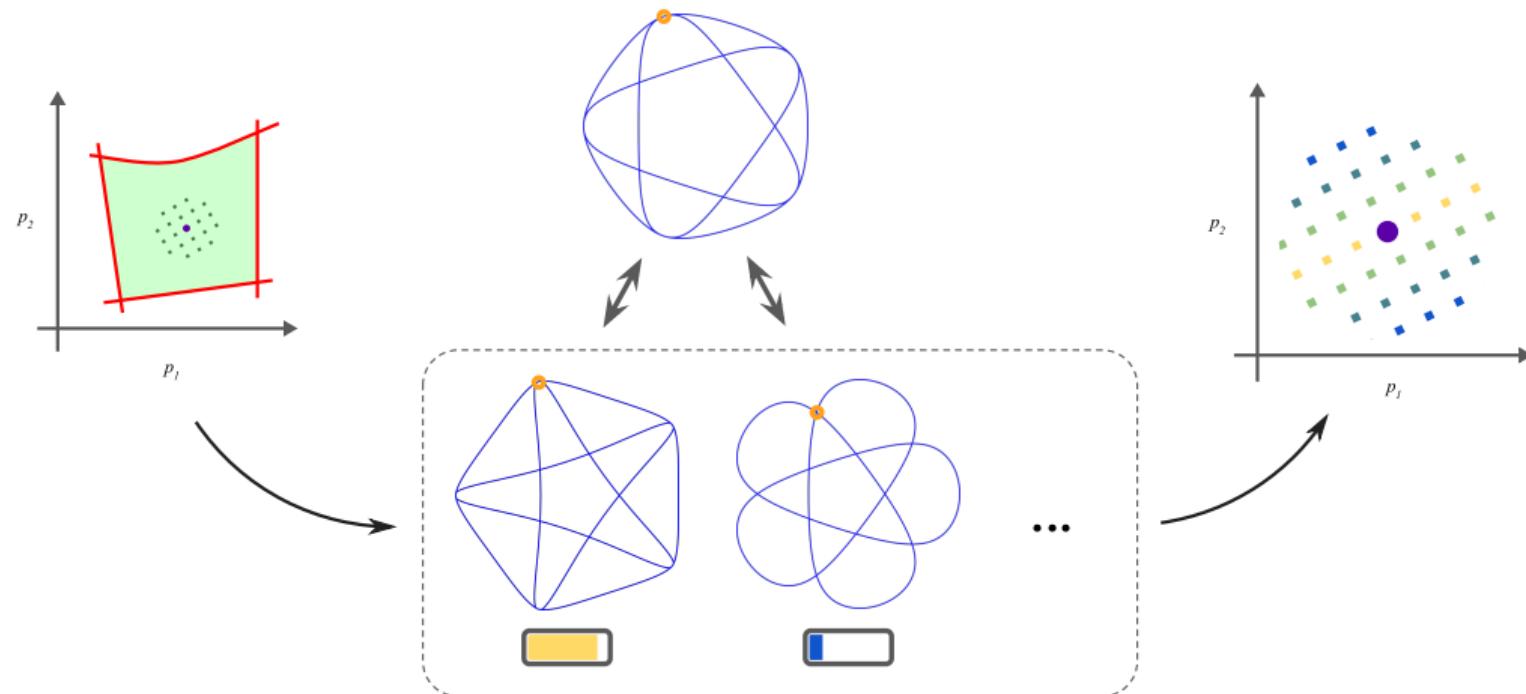
Implementation

Invariance score



Implementation

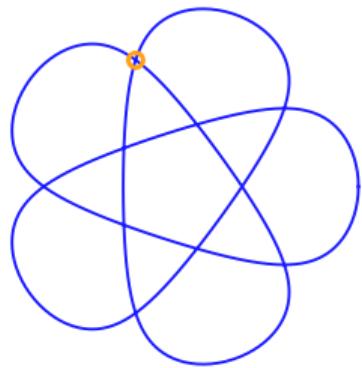
Invariance score



Implementation

Assigning an invariance score

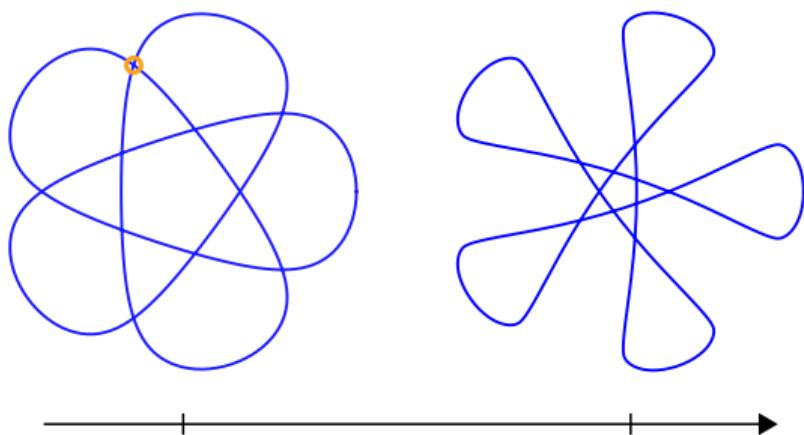
The tracking problem



Implementation

Assigning an invariance score

The tracking problem

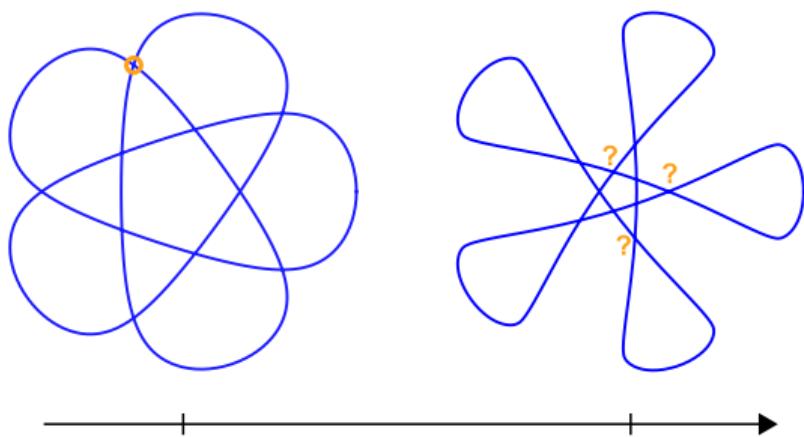


Continuous transformation

Implementation

Assigning an invariance score

The tracking problem

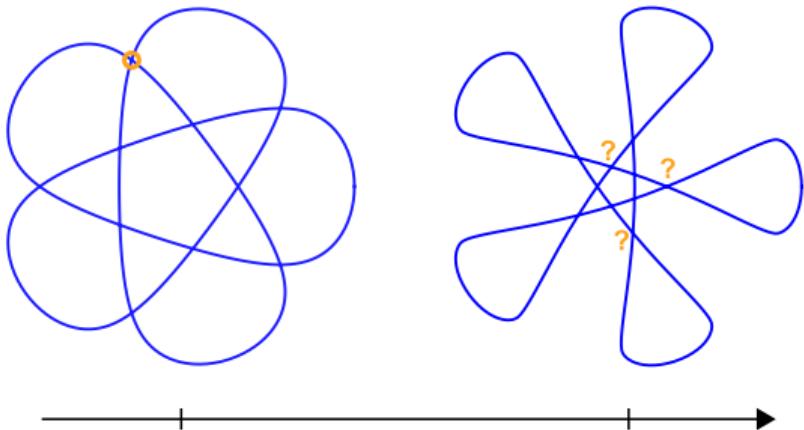


Continuous transformation

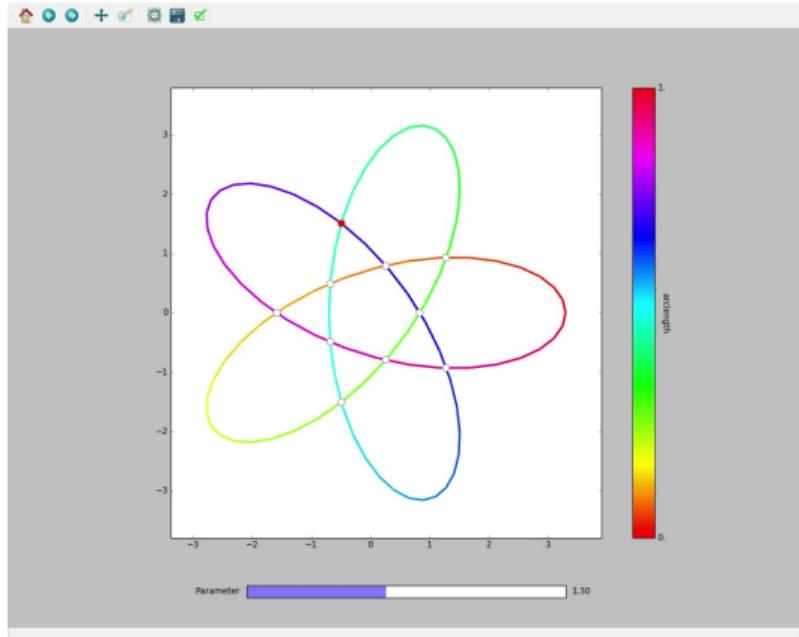
Implementation

Assigning an invariance score

The tracking problem

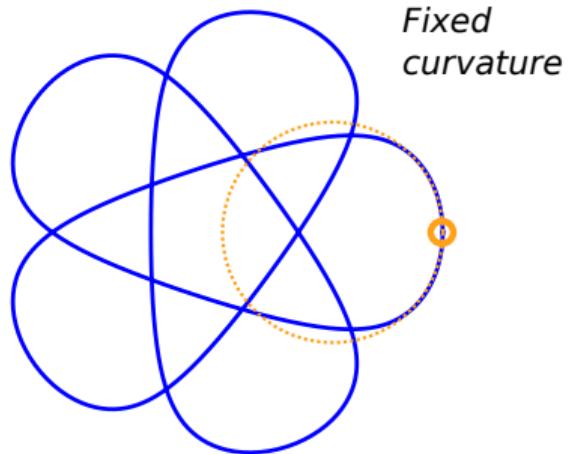
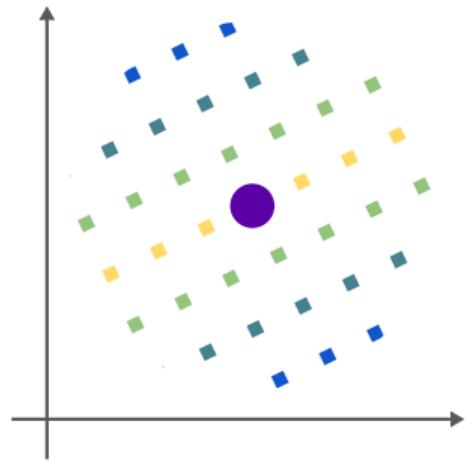


Continuous transformation



Implementation

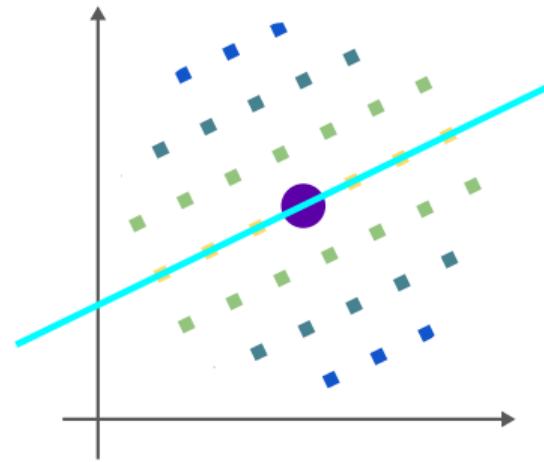
Approximating the invariant space



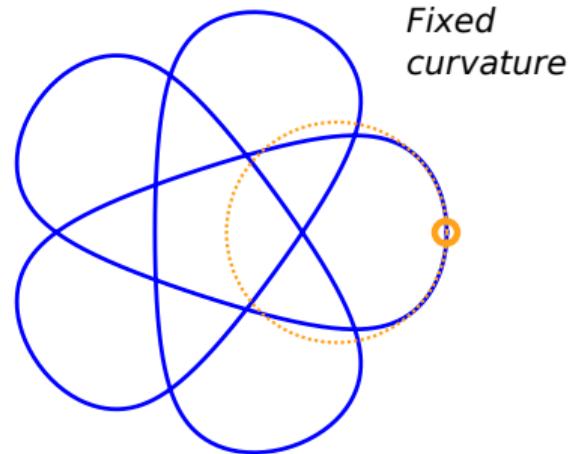
*Fixed
curvature*

Implementation

Approximating the invariant space

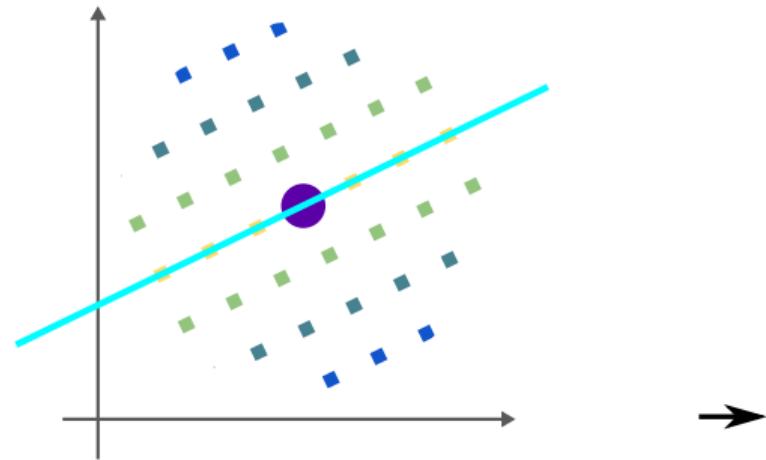


Weighted Principal Component Analysis

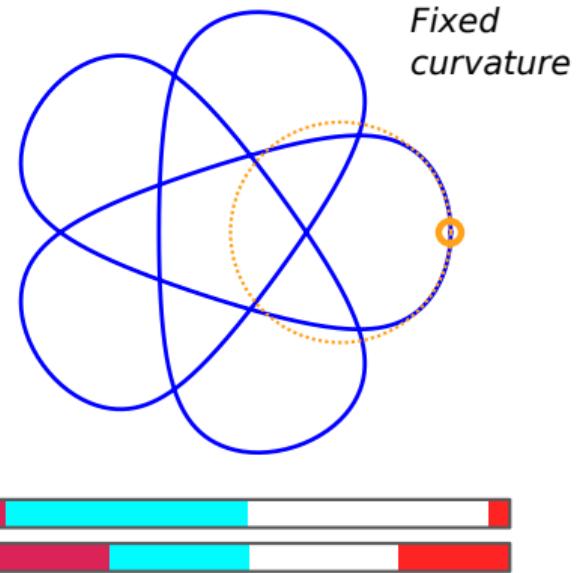


Implementation

Approximating the invariant space

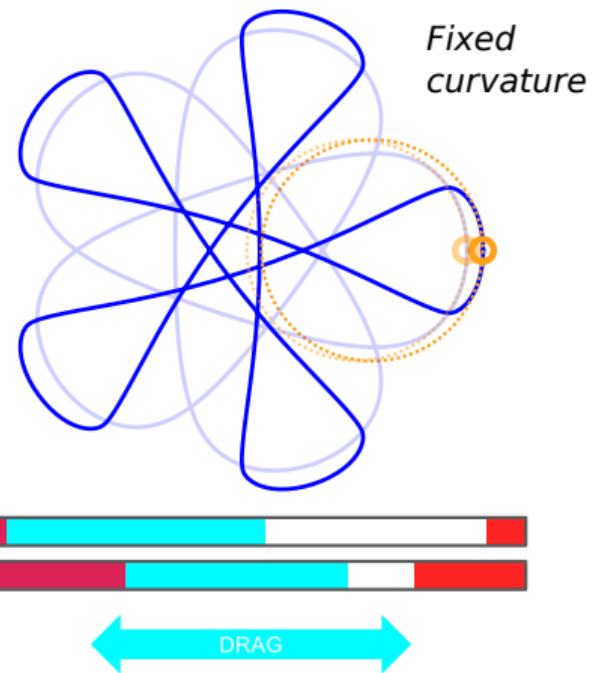
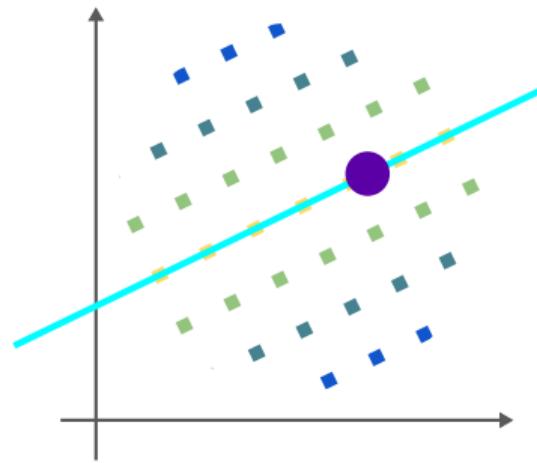


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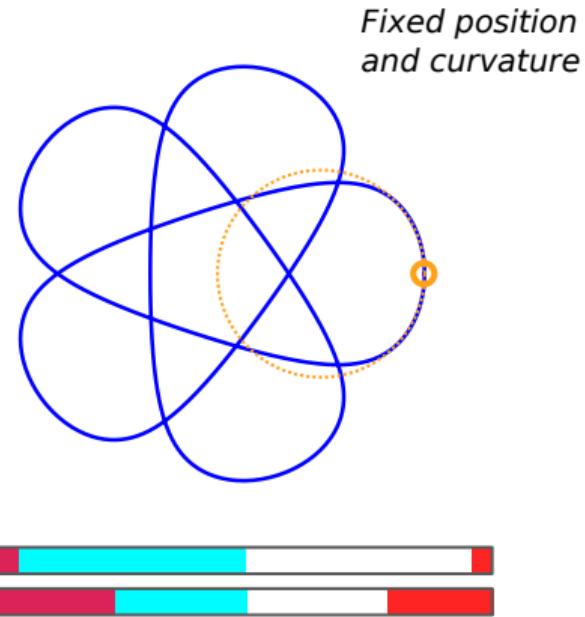
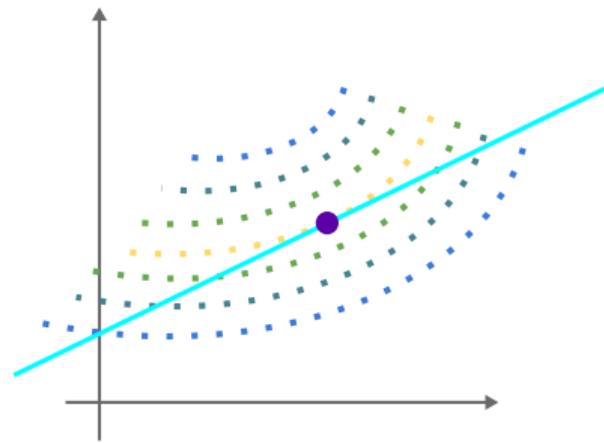
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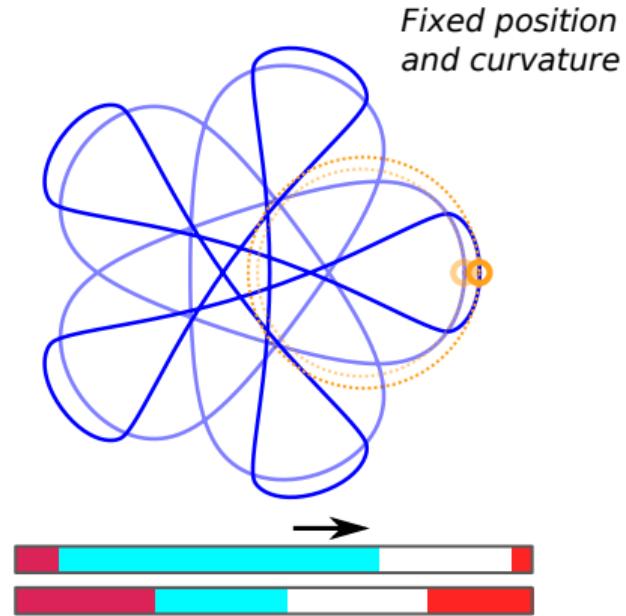
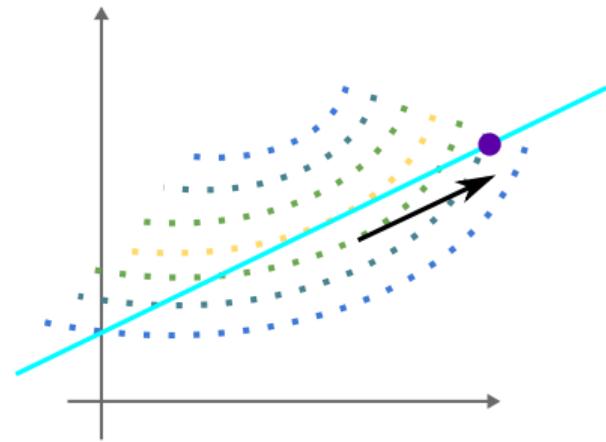
Implementation

Updating the approximation



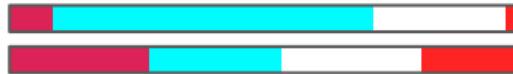
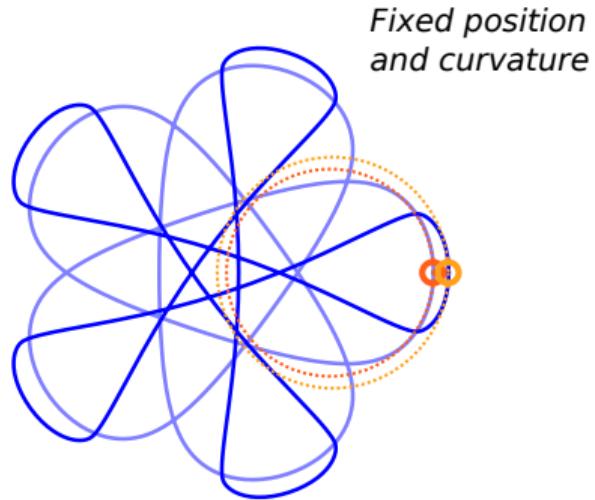
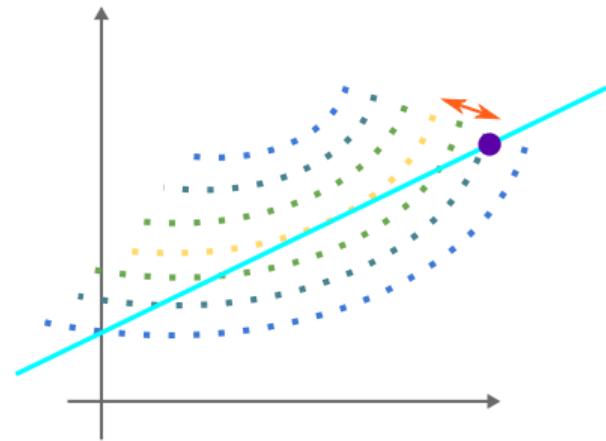
Implementation

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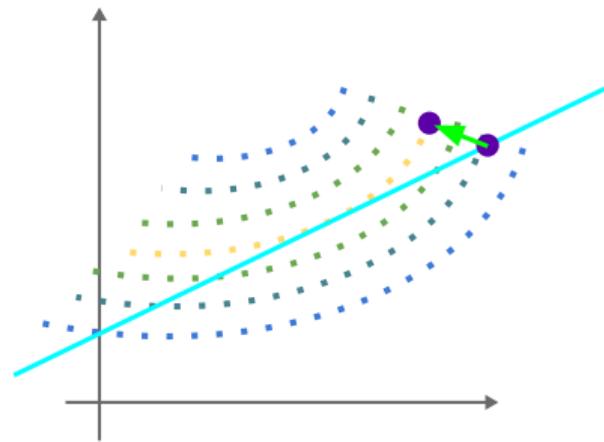
Implementation

Updating the approximation

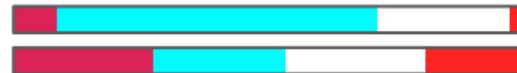
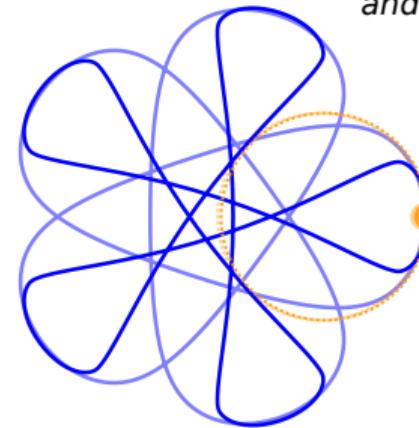


Implementation

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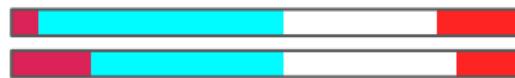
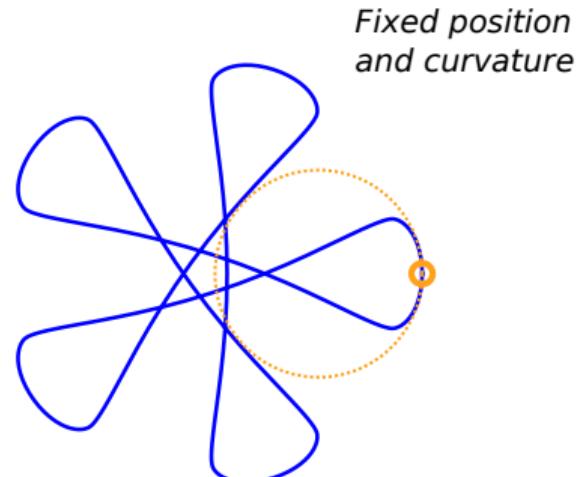
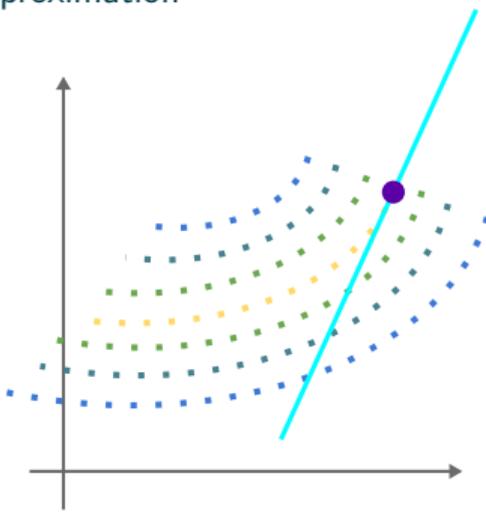


*Fixed position
and curvature*



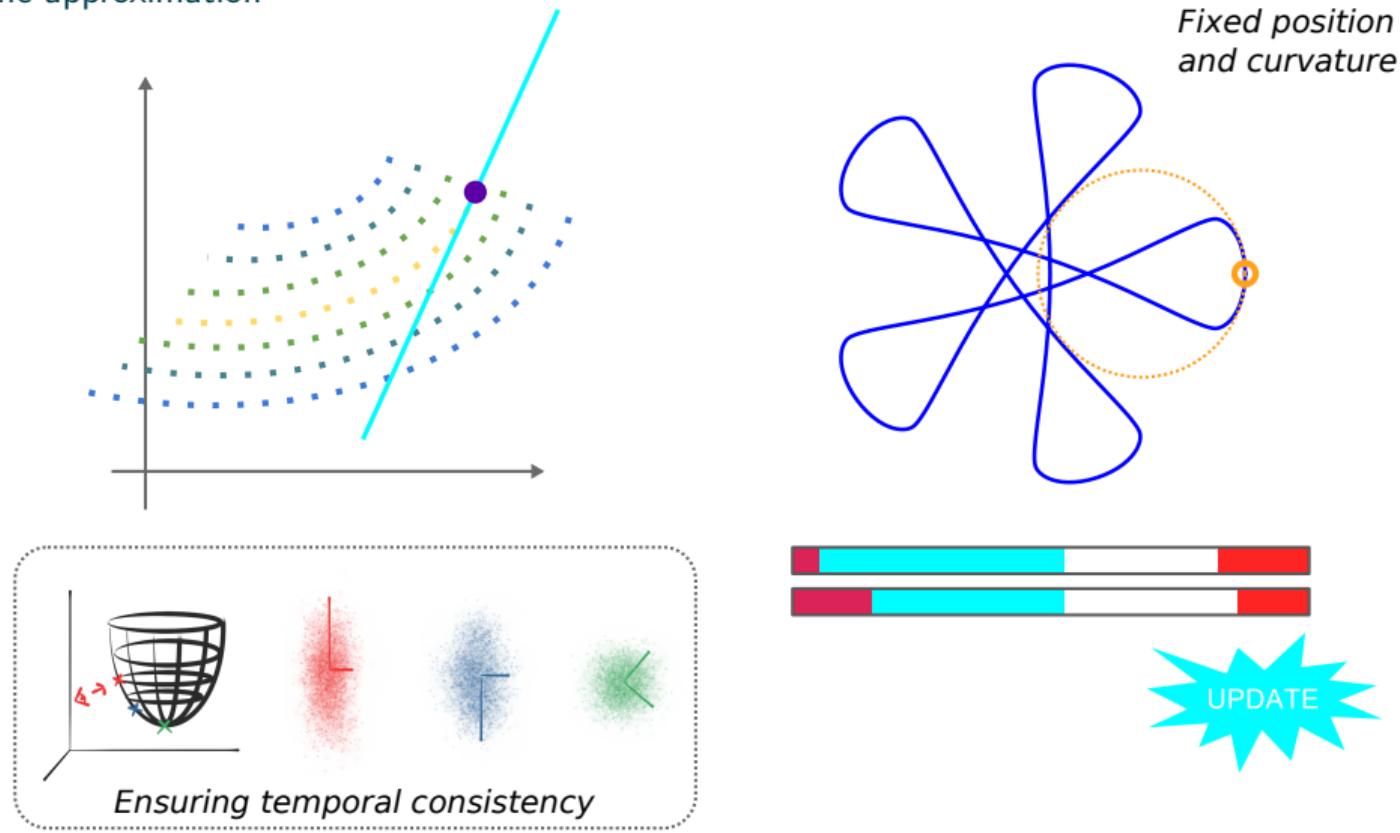
Implementation

Updating the approximation



Implementation

Updating the approximation



Outline

Introduction

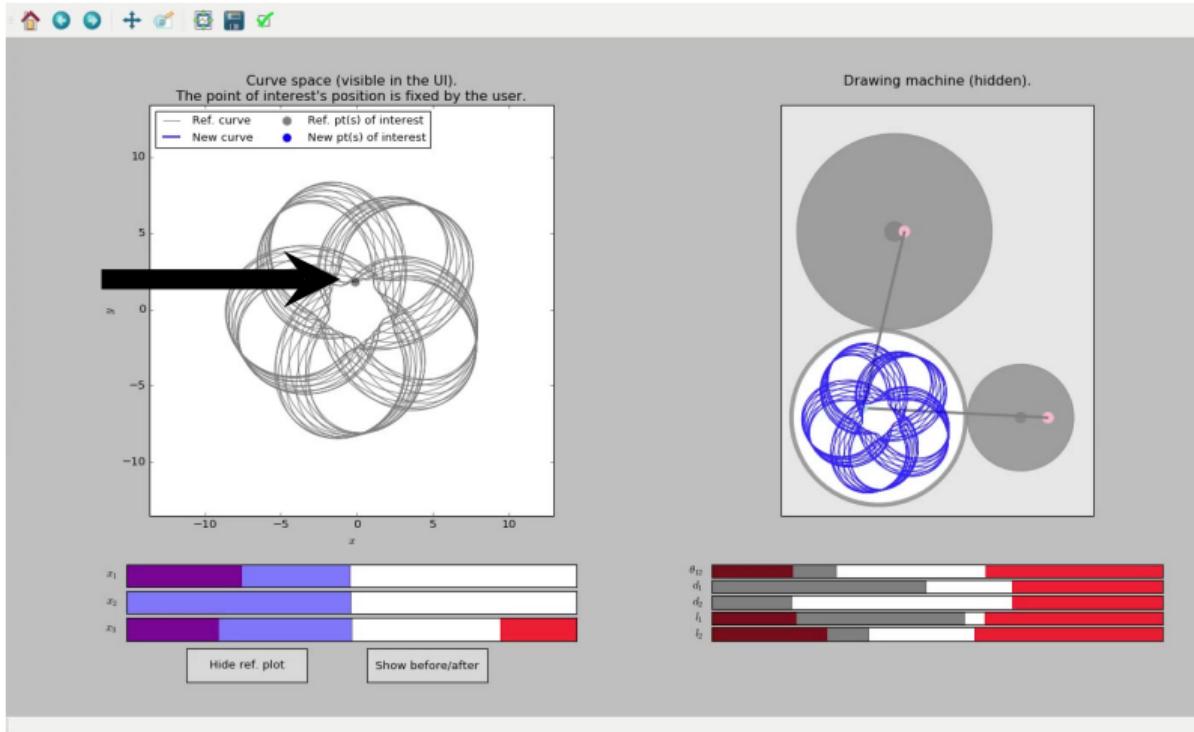
Method

Results

Conclusion

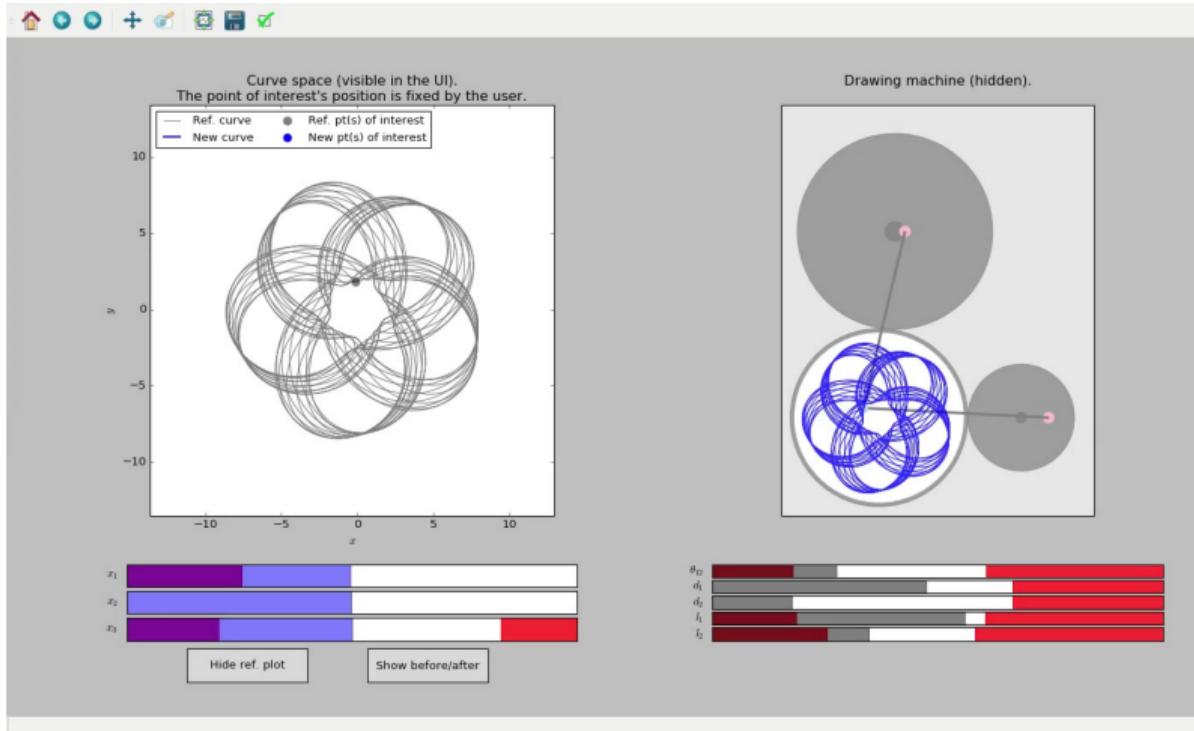
Validation

Demo: fixed point position



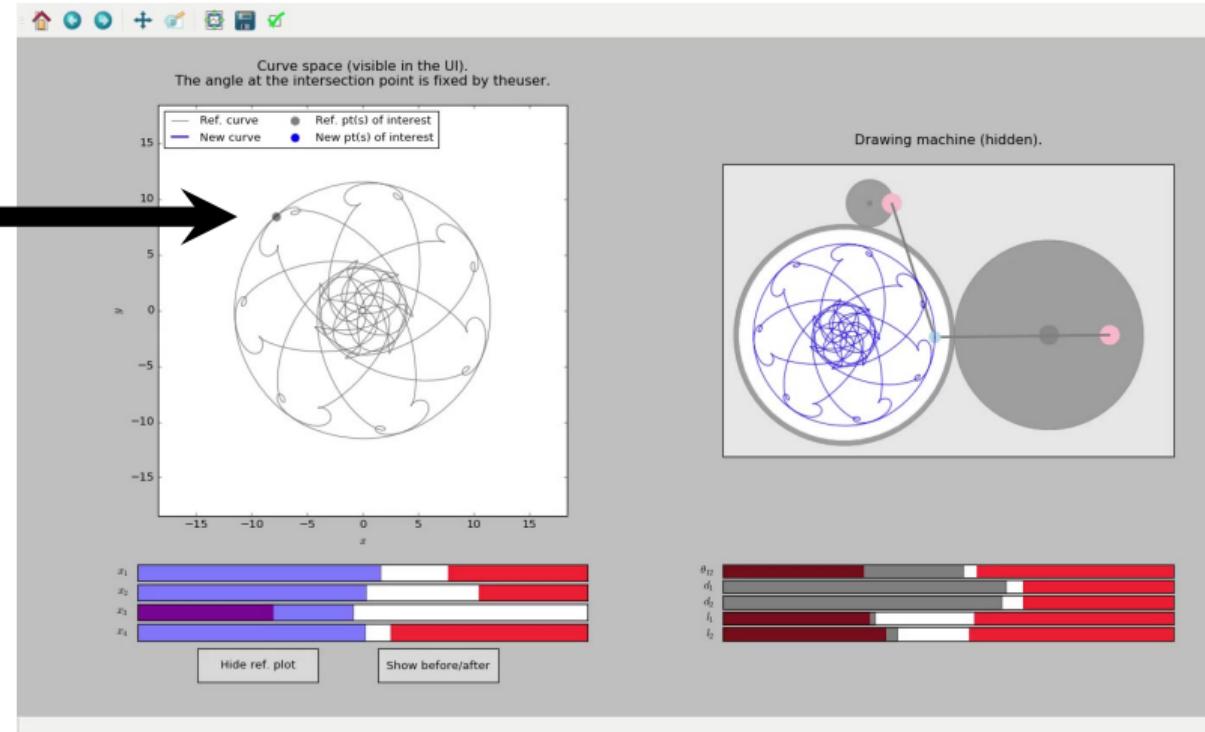
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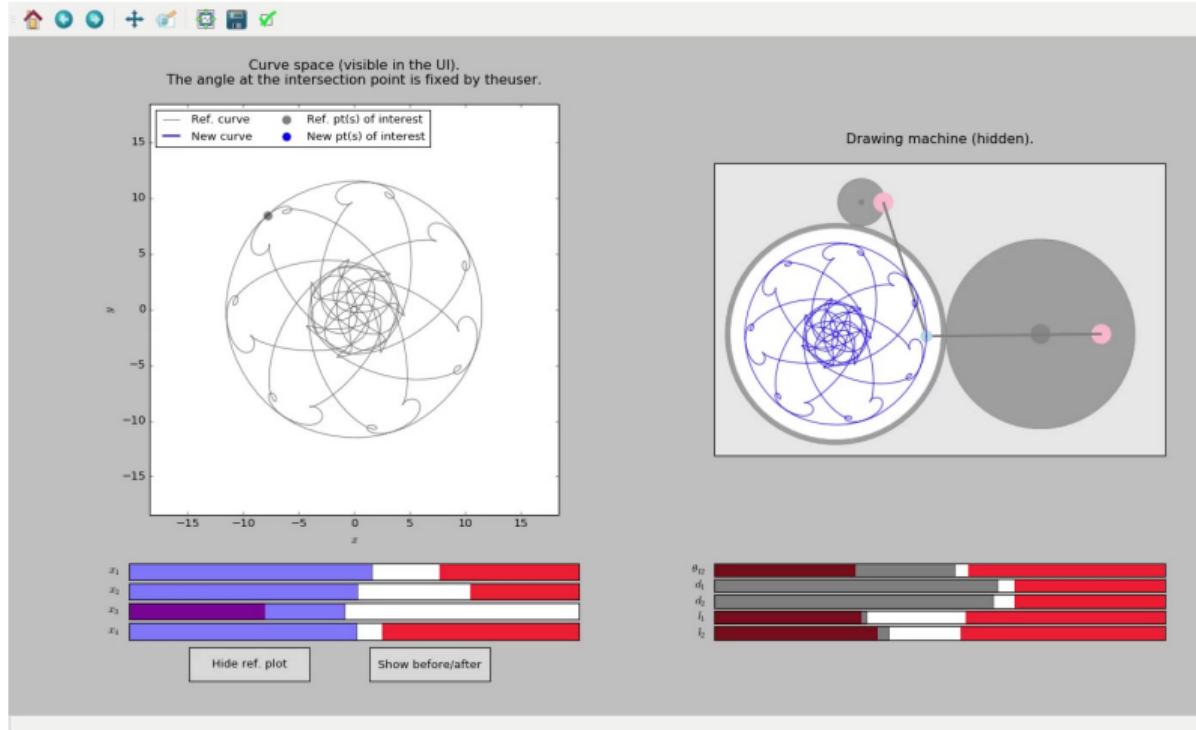
Validation

Demo: fixed curve tangency



Validation

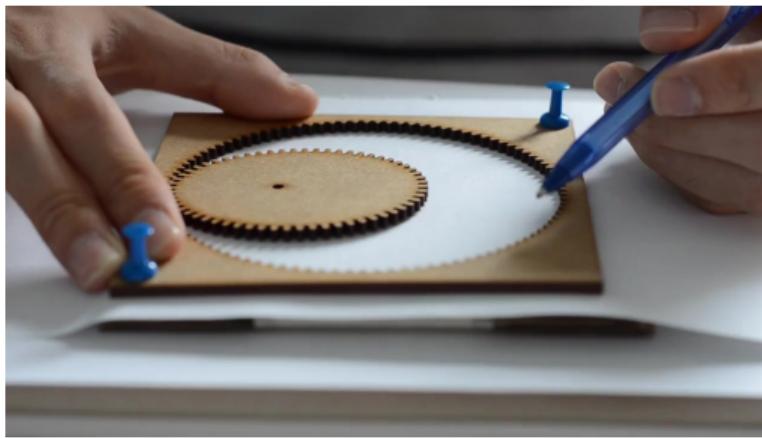
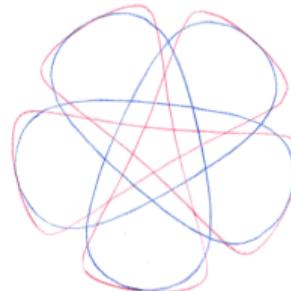
Demo: fixed curve tangency



Validation

Fabrication

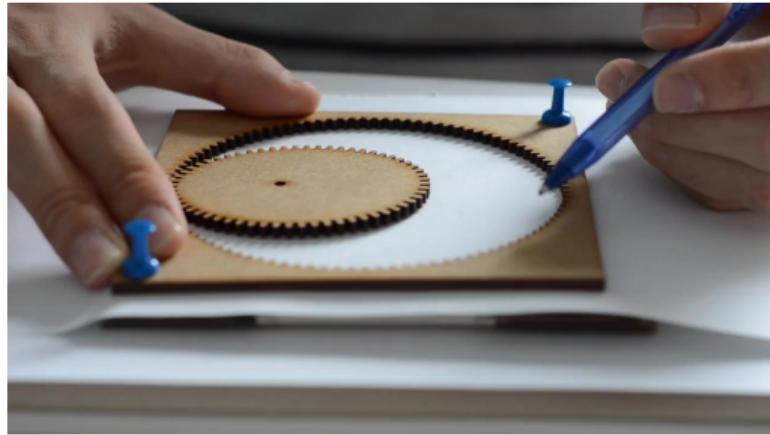
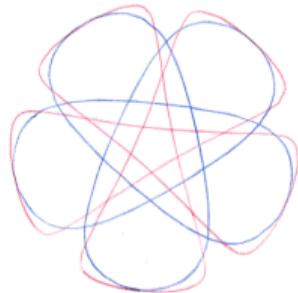
Elliptic Spirograph



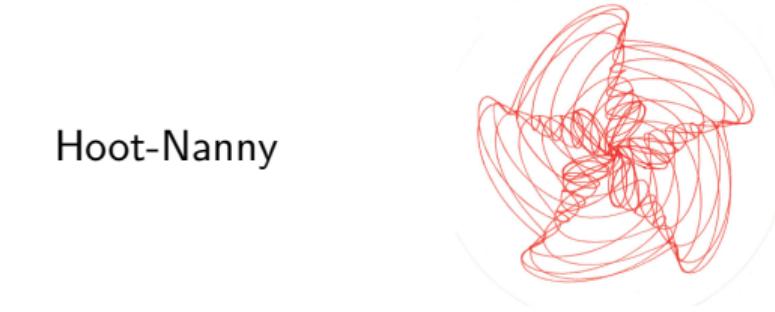
Validation

Fabrication

Elliptic Spirograph



Hoot-Nanny



Limitations and future work

Primary:

- ▶ Add hints to help visualize the effect of each slider

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- ▶ Take physical effects into account (friction, gear play)

Outline

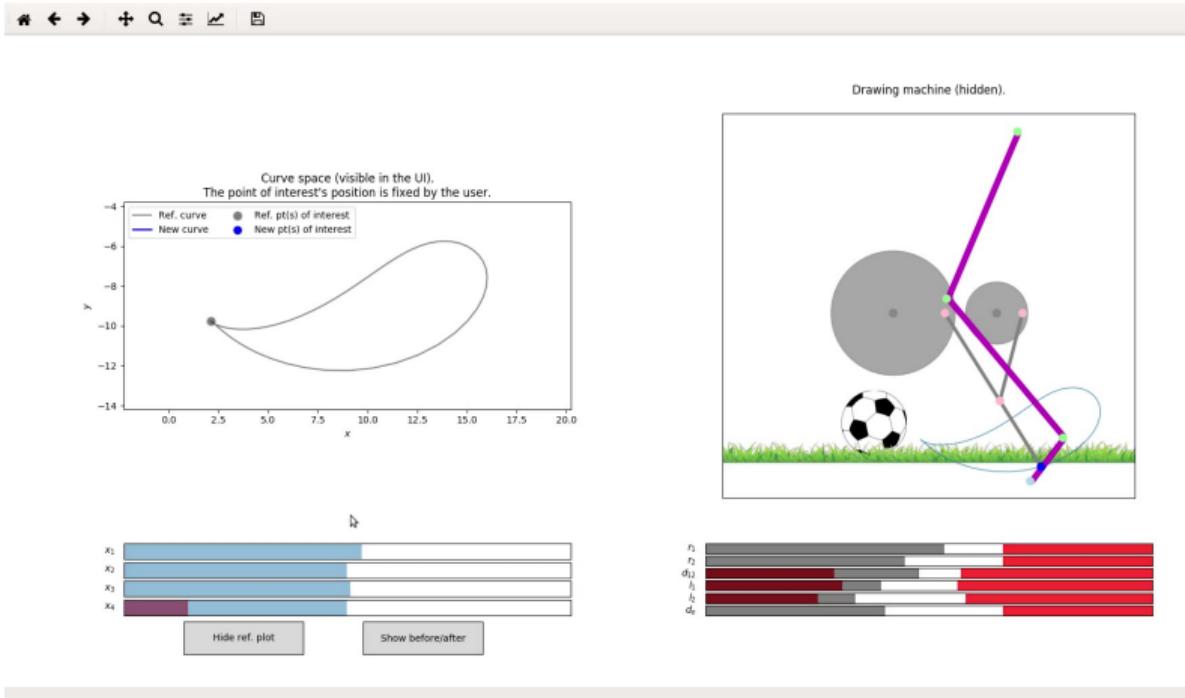
Introduction

Method

Results

Conclusion

Conclusion



Project page [with code next week]:
<http://geometry.cs.ucl.ac.uk/projects/2017/constrained-exploration/>